

GPIB-COM

User Manual

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National Instruments Corporation
6504 Bridge Point Parkway
Austin, TX 78730-5039

(512) 794-0100
(800) IEEE-488 (toll-free U.S. and Canada)
Technical support fax: (512) 794-5678

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FCC/DOC Radio Frequency Interference Compliance

This equipment generates and uses radio frequency energy and, if not installed and used in strict accordance with the instructions in this manual, may cause interference to radio and television reception. This equipment has been tested and found to comply with (1) the limits for a Class B computing device, in accordance with the specifications in Part 15 of U.S. Federal Communications Commission (FCC) Rules, and (2) the limits for radio noise emissions from digital apparatus set out in the Radio Interference Regulations of the Canadian Department of Communications (DOC). These regulations are designed to provide reasonable protection against interference from the equipment to radio and television reception in residential areas.

There is no guarantee that interference will not occur in a particular installation. However, the chances of interference are much less if the equipment is used according to this instruction manual.

If the equipment does cause interference to radio or television reception, which can be determined by turning the equipment on and off, one or more of the following suggestions may reduce or eliminate the problem.

- Operate the equipment and the receiver on different branches of your AC electrical system.
- Move the equipment away from the receiver with which it is interfering.
- Relocate the equipment with respect to the receiver.
- Reorient the receiver's antenna.
- Be sure that the equipment is plugged into a grounded outlet and that the grounding has not been defeated with a cheater plug.

If necessary, consult National Instruments or an experienced radio/television technician for additional suggestions. The following booklet prepared by the FCC may also be helpful: *How to Identify and Resolve Radio-TV Interference Problems*. This booklet is available from the U.S. Government Printing Office, Washington, DC 20402, Stock Number 004-000-00345-4.

Preface

Introduction to the GPIB-COM

The GPIB-COM is a high-performance talk/listen interface board that makes communication possible between IEEE-488 devices and IBM personal computers and compatibles (hereafter referred to as PCs) equipped with software that uses the serial ports.

Organization of This Manual

This manual is divided into the following sections:

Section One, *Introduction*, contains a brief description of the GPIB-COM including a listing of its features, accessories, and components.

Section Two, *Configuration and Installation*, describes how to configure and install the GPIB-COM into your system.

Section Three, *Function Description*, shows a block diagram of the GPIB-COM and describes the functional components of the GPIB-COM.

Section Four, *Running Diagnostic Tests*, describes how to run the diagnostic tests that are shipped with the GPIB-COM.

Section Five, *Programming the GPIB-COM*, presents a description of the GPIB-COM Serial Port Emulator registers and information on programming the IBM serial adapter.

Appendix A, *Specifications*, lists the specifications of the GPIB-COM board.

Appendix B, *Multiline Interface Command Messages*, contains an ASCII chart and a list of the corresponding GPIB messages.

Appendix C, *Operation of the GPIB*, describes GPIB terminology and protocol for users unfamiliar with the GPIB.

Related Documents

The following documents contain information that may be helpful as you read this manual:

- *ANSI/IEEE Std 488-1978, IEEE Standard Digital Interface for Programmable Instrumentation*
- *IBM Options and Adapters Manual*
- *IBM PC Technical Reference Manual*
- *IBM Disk Operating System Manual*
- *INS8250A Data Sheet*, National Semiconductor

Abbreviations Used in This Manual

The following abbreviations are used in the text of this manual.

\leq	is less than or equal to
\geq	is greater than or equal to
\pm	plus or minus
A	ampere
C	Celsius
hex	hexadecimal
in.	inch
I/O	input/output
kbyte	1000 bytes
m	meter
Mbyte	megabyte
MHz	megahertz
msec	millisecond
r	read
r/w	read/write
sec	second
V	volt
VDC	volts direct current
w	write

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Section One

Introduction

This section contains a brief description of the GPIB-COM interface and a list of its characteristics and components.

GPIB-COM Characteristics

The National Instruments GPIB-COM is a high-performance talk/listen interface that converts data between a standard serial port format and IEEE-488 General Purpose Interface Bus (GPIB) format for use with IEEE-488 printers and plotters. It can be used with any serial port software on the PC. The GPIB-COM looks like a standard serial port to the IBM PC operating system and software. It can be used to interface IEEE-488 devices to any PC software that uses the serial ports.

The GPIB-COM has the following hardware features:

- emulates the standard PC serial adapter interface so that no additional software is needed
- can be configured as either COM1, COM2, COM3, or COM4
- compatible with any software using the serial ports on the IBM PC and its compatibles
- transparent addressing of unaddressed Talkers and Listeners
- choice of talk-only mode for use with listen-only printers and plotters
- choice of REN mode, which operates an instrument in the remote mode
- choice of SRQ enable, which allows monitoring of asynchronous service requests
- choice of IFC mode, which sends an interface clear when the computer is powered on

Figure 1-1 shows the GPIB-COM interface board.

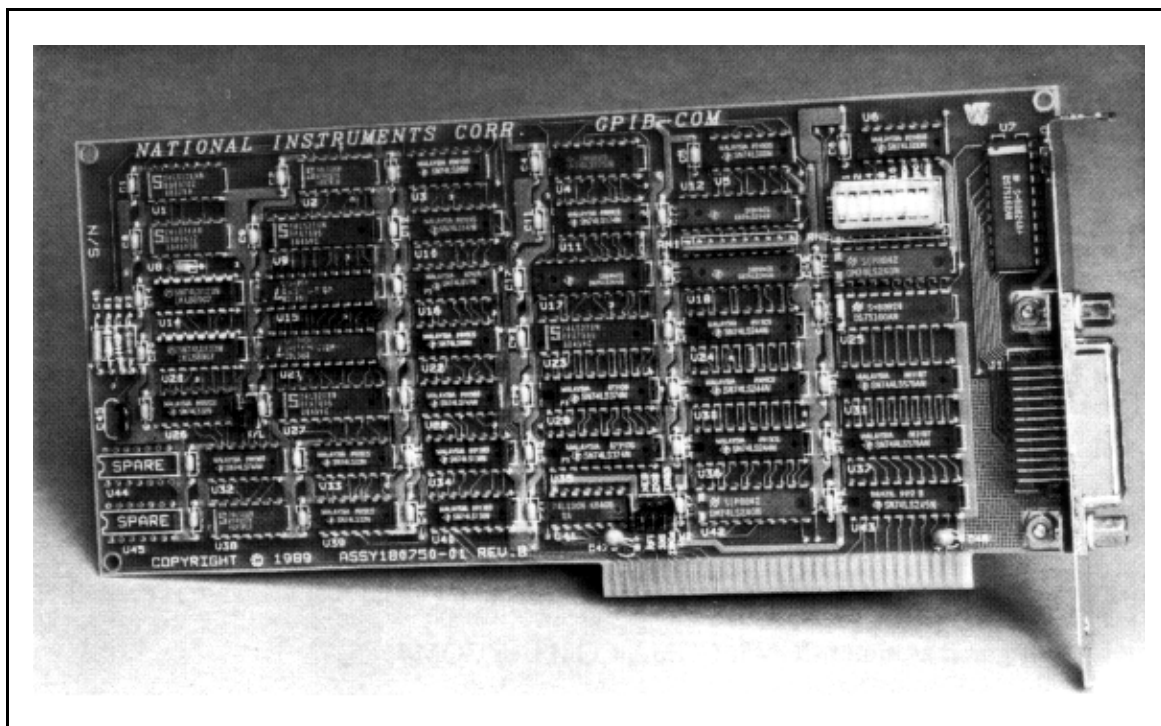


Figure 1-1. GPIB-COM Board

What Your Kit Should Contain

Your kit should contain the following components:

Item	Part Number
GPIB-COM interface board	180750-01
<i>GPIB-COM User Manual</i>	320197-01
GPIB-COM Diagnostic Test Diskette	420212-45
<p>Note: The GPIB-COM Diagnostic Test Diskette contains the com.exe diagnostic test that is described in Section Four, <i>Running Diagnostic Tests</i>.</p>	

Make sure each of these items is in your kit. If any item is missing, contact National Instruments.

Optional Equipment

Item	Part Number
Double-Shielded Cables: GPIB Type X2 Cable - 1 m GPIB Type X2 Cable - 2 m GPIB Type X2 Cable - 4 m	763061-01 763061-02 763061-03
* In order to meet FCC emission limits for a Class B device, you must use a shielded GPIB cable. Operating this equipment with a non-shielded cable may cause interference to radio and television reception in residential areas.	

Section Two

Configuration and Installation

This section contains information on how to configure and install the GPIB-COM into your system.

Configuration

Figure 2-1 shows the locations of the GPIB-COM configuration jumpers and switches.

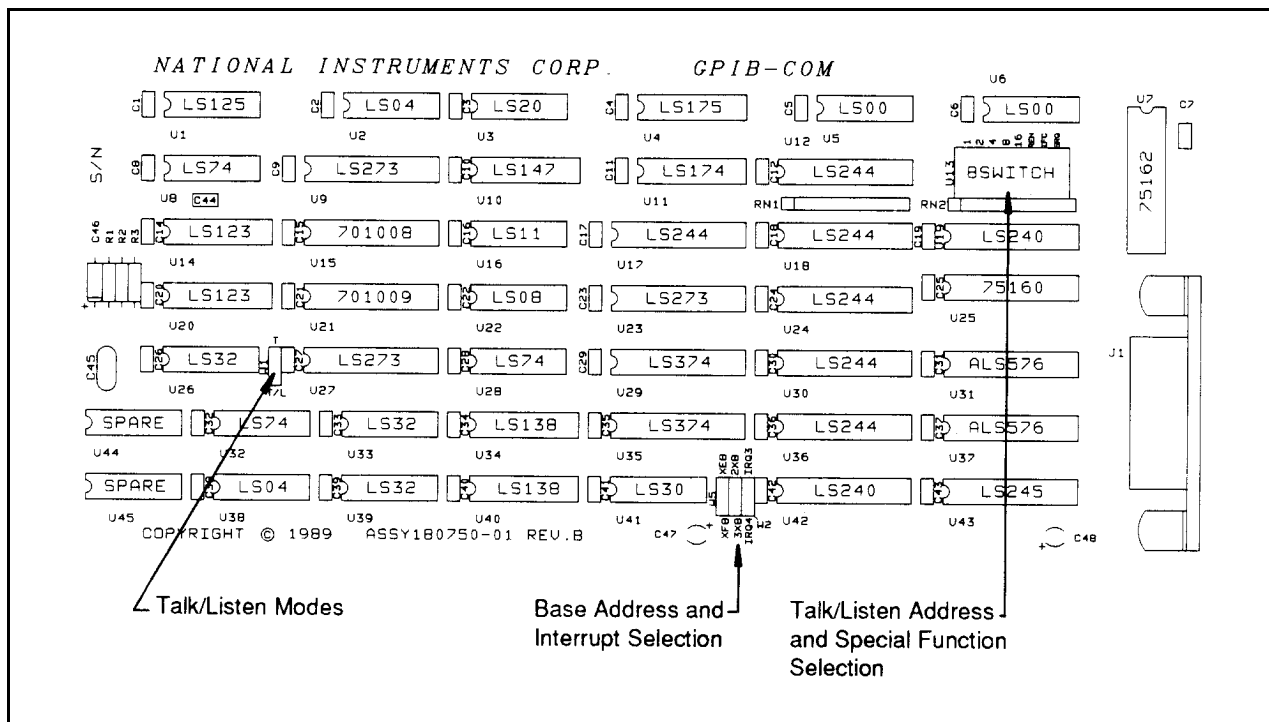


Figure 2-1. GPIB-COM Parts Locator Diagram

When installing the GPIB-COM you must determine which serial port the GPIB-COM board will respond to and select the appropriate base address and interrupt level. The GPIB-COM can be configured to one of four base addresses:

- 3F8 for Serial Port 1
- 2F8 for Serial Port 2
- 3E8 for Serial Port 3
- 2E8 for Serial Port 4

Note: DOS and BIOS only recognize base addresses 3F8 and 2F8.

The GPIB-COM is shipped from the factory set to 3F8. It must be reconfigured to another base address if another device (such as a printer adapter card or a built-in serial port) is already at that address.

DOS has reserved device names for the serial ports it finds in the system: COM1 and COM2. The serial port adapters are named in the order in which they are found. When the computer is powered on, DOS searches the serial port addresses for installed adapters. It first searches 3F8, then 2F8. If only one device is installed, that device is named COM1 regardless of what its I/O address is. If there is more than one serial device installed, the first one found is assigned COM1 and the second one found is assigned COM2.

Some communications software also recognizes COM3 (base address 3E8) and COM4 (base address 2E8). If you wish to use COM3 or COM4, set the jumpers to the desired base address as shown in Figure 2-2. DOS and BIOS do not recognize COM3 or COM4. Consult your software documentation to see which interrupt level, if any, is required. If interrupts are not used, the jumper can be removed or stored with only one side on a pin.

The GPIB-COM may need to be reconfigured if its interrupt level conflicts with another device. If the base I/O address of the GPIB-COM does not conflict with any other device in your computer and the GPIB-COM still does not work with your software package, reconfigure the GPIB-COM to a different interrupt level.

Table 2-1 shows the standard base I/O address and interrupt level for each serial port.

Table 2-1. IBM PC Serial Port Adapters

Name of Port	Base I/O Address (hex)	Interrupt Level
Serial Port 1	3F8	4
Serial Port 2	2F8	3
Serial Port 3	3E8	Not Used
Serial Port 4	2E8	Not Used

Switch and Jumper Settings

Table 2-2 shows the factory settings and optional configurations for the switches and jumpers on the GPIB-COM.

Table 2-2. Factory Default Settings and Optional Configurations

GPIB-COM	Default	Optional
Base I/O Address	3F8	2F8, 3E8, 2E8
Interrupt Level	4	3

If you need to change the factory settings, continue on. If you do not need to change the factory settings, skip to *Installation* later in this section.

Base I/O Address and Interrupt Selection

The base I/O address and interrupt line used by the GPIB-COM are determined by the jumpers located at positions W2 and W5. The jumpers are set at the factory for base I/O address 3F8 hex and interrupt level 4.

Figure 2-2 shows the four possible combinations of jumper settings.

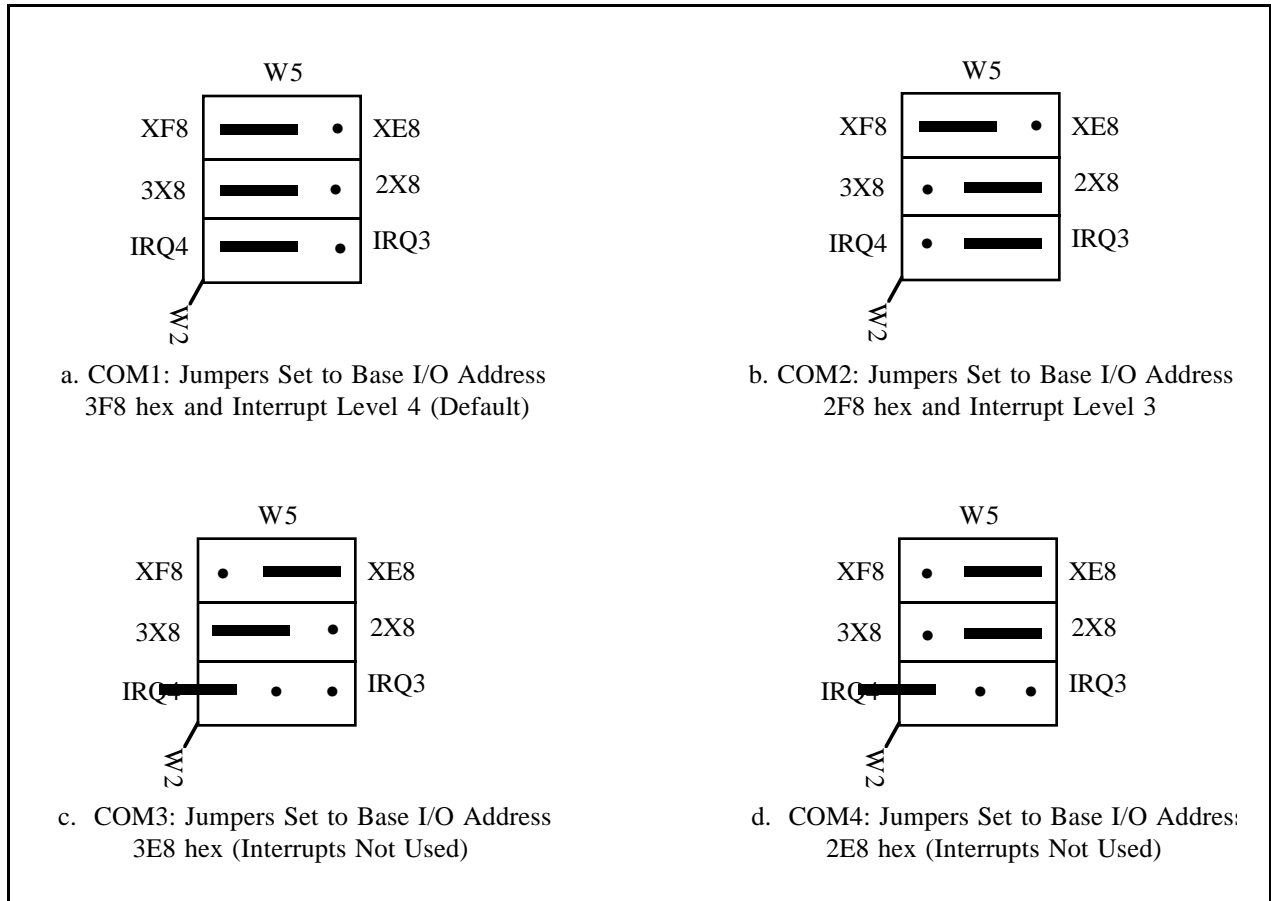


Figure 2-2. Possible Settings for GPIB-COM Jumpers

Talk/Listen Modes

If you are using your GPIB-COM with a listen-only printer or plotter, you can configure the GPIB-COM for a talk-only mode. In this mode, the GPIB-COM is always a Talker and never sends any interface commands. To set the talk-only mode, change jumper W1 from T/L to T as shown in Figure 2-3:

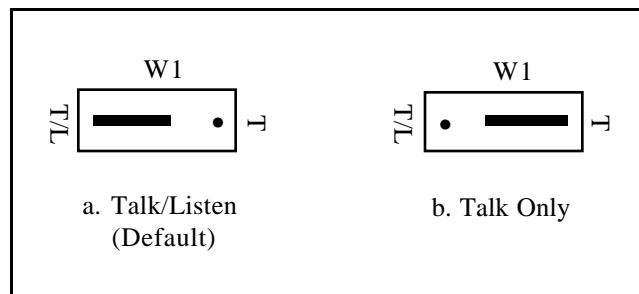


Figure 2-3. Jumper W1 Settings

Talk/Listen Address and Special Function Selection

The GPIB-COM interface board has eight onboard DIP switches you can use to configure the GPIB controller responsibilities. In the talk/listen mode, the first five switches set the talk or listen address of the external device(s) that will be attached to the GPIB-COM. In the talk-only mode, the GPIB-COM does not send a talk or listen address.

The three remaining switches (REN, IFC, and SRQ) have the following special functions:

Note: An asterisk (*) after a signal name indicates that the signal is inverted (negative logic).

- REN* Asserts/unasserts the Remote Enable (REN) line that places an instrument in remote mode. The ON position enables REN. The OFF position disables REN.
- IFC* Enables/disables the Interface Clear (IFC) option on the GPIB-COM. If enabled, the GPIB-COM issues an IFC when it is initialized. The ON position enables IFC on initialization. The OFF position holds IFC unasserted.
- SRQ* Enables/disables the Service Request (SRQ) option. If enabled, the GPIB-COM monitors the SRQ line through the Parity Error Bit (PE) in the Line Status Register. When the switch is ON, the PE bit reflects the status of the SRQ line. When the switch is OFF, the PE bit is always clear.

The GPIB-COM factory default switch configuration is for device listen address 5, REN* not asserted, IFC* enabled, and SRQ* enabled. Figure 2-4 shows the factory default switch settings for the GPIB-COM.

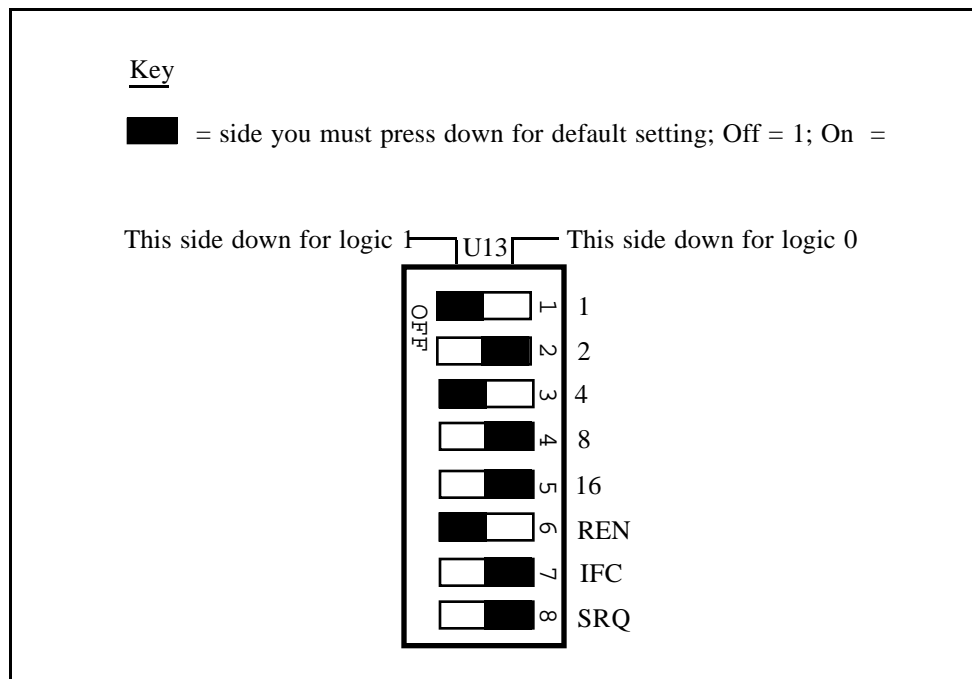


Figure 2-4. Switch Setting for REN* OFF, IFC* ON, SRQ* ON, and Listen Address 5 (Default Setting)

Figure 2-5 shows the switch configuration needed when using a device with listen address 10 hex. The listen address varies with each device so check the listen address of your device and set these five bits accordingly.

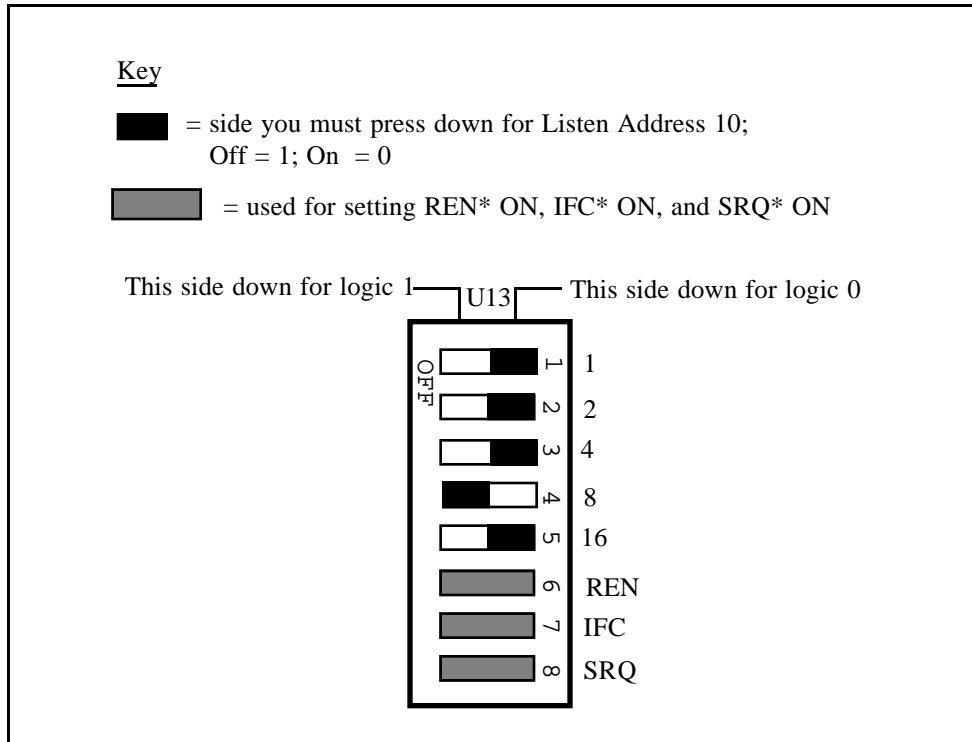


Figure 2-5. Listen Address Setting for Listen Address 10 Hex

Figure 2-6 shows the switch configuration for REN* asserted, IFC* disabled, and SRQ* disabled.

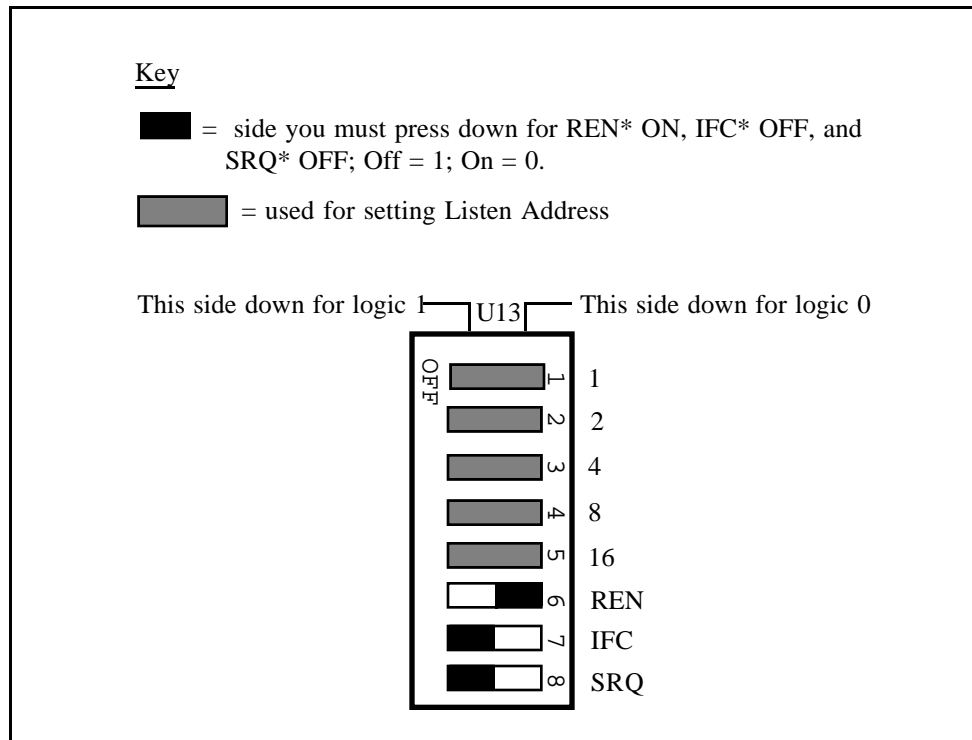


Figure 2-6. Switch Setting for REN* ON, IFC* OFF, and SRQ* OFF

Installation

Once you have changed, verified, and recorded the switches and jumper settings, you are ready to install the GPIB-COM.

The following steps are general installation instructions. Consult the user manual or technical reference manual of your personal computer for specific instructions and warnings.

1. Turn off your computer.
2. Remove the plug from its power source.
3. Remove the top cover or access port to the I/O channel.
4. Remove the expansion slot cover on the back panel of your computer.
5. Insert the GPIB-COM in an unused full-length slot with the IEEE-488 receptacle sticking out of the opening of the back panel. It may be a tight fit, but do not force the board into place.
6. Screw the right angle mounting bracket of the GPIB-COM to the back panel rail of your computer.

7. Check the installation.
8. Replace the expansion slot cover of your computer.
9. Connect the GPIB cable to the GPIB-COM.

Special Considerations When Using the GPIB-COM

The GPIB-COM does not support XON/XOFF protocols. If your application software uses XON/XOFF protocols, send your printer and plotter output to a file on disk. From DOS, send your file to the GPIB-COM by using the DOS command:

```
copy filename COM1:
```

```
copy filename COM2:
```

The DOS MODE command is used to set the RS-232 parameters that will be used when COM1 and COM2 are accessed through DOS. Sometimes a timeout error may occur when writing through the GPIB-COM to a slow device such as a printer or a plotter. If this happens, use the MODE command to disable the timeout function by typing `MODE COM1:12,,,,P`. Some software applications use the COM port baud rate setting to control the data transmission speed. To obtain the fastest possible transfer rates, set the baud rate setting to 9600 baud. The P at the end disables the timeout. For more information on the MODE command, refer to the *IBM Disk Operating System Manual*. This command can also be used in an `autoexec.bat` file to disable timeouts when you start up the computer.

Section Three

Function Description

This section contains a block diagram of the GPIB-COM, followed by a description of each of its functional components.

The GPIB-COM Interface

The GPIB-COM is a completely transparent interface between GPIB devices and any IBM PC software that uses serial ports. A set of I/O registers identical to those on the standard IBM serial adapter is used. On the GPIB side, the GPIB-COM includes a limited subset of interface functions that address a GPIB device to listen when the computer sends data to the serial port and to talk when the computer is waiting to receive data from the serial port. In order to be able to respond immediately to commands and data sent to the serial port, the GPIB-COM must be the GPIB System Controller and cannot work with other Controllers present.

Figure 3-1 shows a block diagram of the GPIB-COM.

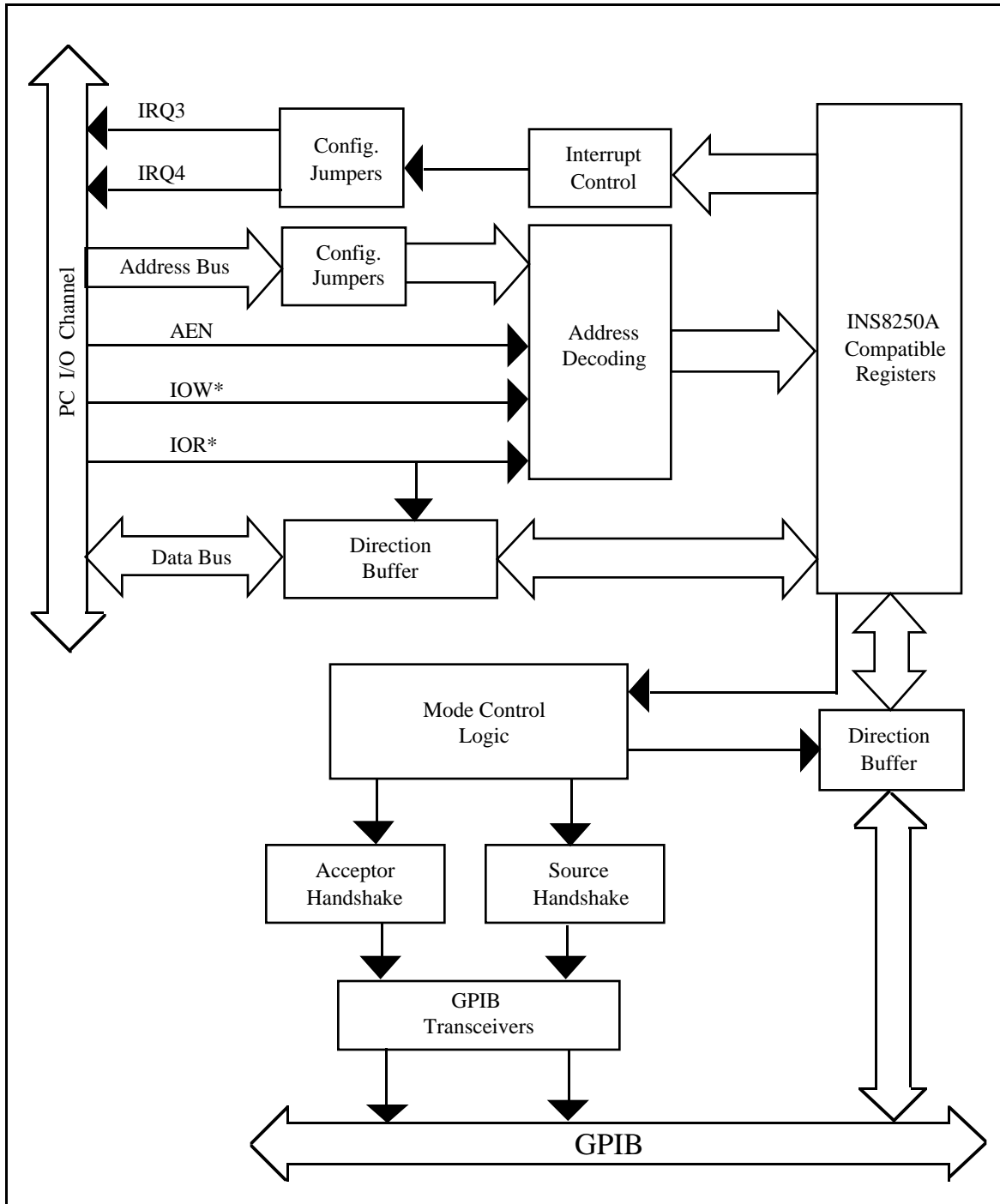


Figure 3-1. Block Diagram of GPIB-COM

GPIB-COM Components

The interface consists of the following functional components:

- Address Decoding
- Configuration Jumpers
- INS8250A Compatible Registers
- GPIB Acceptor and Source Handshaking
- Mode Control Logic
- Interrupt Control Logic
- Direction Buffers
- GPIB Transceivers

Address Decoding

Address decoding monitors the PC address bus to recognize when a GPIB-COM address is present and enables a read and/or write to its registers.

Configuration Jumpers

These onboard jumpers select the base address, GPIB controller mode, and interrupt request line used by the GPIB-COM.

INS8250A Compatible Registers

The main component of an IBM PC compatible serial adapter is an INS8250A Asynchronous Communications chip or its equivalent, which handles RS-232 communication. The INS8250A compatible registers on the GPIB-COM emulate the serial adapter registers so that the GPIB-COM will operate transparently with any serial port driver.

GPIB Acceptor and Source Handshaking

This circuitry converts PC serial port handshaking into GPIB handshaking. This process is completely software-transparent.

Mode Control Logic

This circuitry determines whether the GPIB-COM should be a Talker (and the target device a Listener) or a Listener (and the target device a Talker).

Interrupt Control Logic

This circuitry generates and masks interrupts on GPIB conditions which correspond to the conditions that would cause the INS8250A circuit to generate an interrupt.

Direction Buffers

These buffers control the direction in which data information travels.

GPIB Transceivers

The GPIB-COM is interfaced to the IEEE-488 bus by National Semiconductor 75160A and 75162A transceivers. These integrated circuits are specifically designed to provide power-up/power-down bus protection (glitch-free). The GPIB-COM counts as one IEEE-488 bus load, thereby allowing an additional 14 devices to be connected before exceeding the bus loading restrictions imposed by the IEEE-488.

Section Four

Running Diagnostic Tests

The GPIB-COM Test Commands

The GPIB-COM Diagnostic Tests can be used to verify the configuration of the GPIB-COM and its connection to a GPIB printer or plotter.

To run a GPIB-COM diagnostic test, connect a printer or plotter to the GPIB and run the program `com.exe` from the GPIB-COM diagnostic test diskette. The following message will appear on the screen:

```
NATIONAL INSTRUMENTS GPIB-COM DIAGNOSTIC TESTS
```

```
This program assumes the GPIB-COM is configured at base address  
3F8 (COM1).
```

```
If you reconfigured your GPIB-COM you must change the address  
that this program uses. To do this, enter command c from the  
menu.
```

```
Enter one of the following commands:
```

```
-1 printer test  
-2 plotter test  
-c change COM configuration  
-q quit
```

```
?
```

A short explanation of each command is given in the following paragraphs.

-1 printer test

Select this test to verify the configuration of the GPIB-COM when connecting it to a GPIB ASCII printer. This test will send characters to the printer.

Entering this command returns the prompt:

```
Starting printer test.
```

```
Press any key to stop printing.
```

The printer should begin printing a string of characters. To stop the test, press any key. The following message then appears:

```
Printer test finished.
```

```
Please check output to printer with user manual instructions.
```

The output on the printer should read:

```
NATIONAL INSTRUMENTS GPIB-COM DIAGNOSTIC TEST!"#$%&'()*+,-.
/0123456789:;<=>?@ABCDEFGHIJKLMNPOQRSTUVWXYZ[\]_`abcdefghijkl
mnopqrstuvwxyz{|}~ !"#$%&'()*+,-./0123456789:;<=>?@ABCDEFGHI
JKLMNPOQRSTUVWXYZ[\]_`abcdefghijklmnopqrstuvwxyz{|}~ !"#$%&'
()*+,-./0123456789:;<=>?@ABCDEFGHIJKLMNPOQRSTUVWXYZ[\]_`abcde
fghijklmnopqrstuvwxyz{|}~ !"#$%&'()*+,-./0123456789:;<=>?@ABCDEF
GHIJKLMNPOQRSTUVWXYZ[\]_`abcdefghijklmnopqrstuvwxyz{|}~
```

If the printer does not respond, an error message appears on the screen along with a message telling you to recheck all of your connections and jumper settings. If the test still fails after everything has been checked, write down the error message, if any, and call National Instruments.

-2 plotter test

Select this test to verify the configuration of the GPIB-COM when connecting it to a GPIB HP-GL plotter. This test will send output to the plotter.

When this command is selected, the computer prints the following message:

```
Starting plotter test.
```

As illustrated in Figure 4-1, the plotter begins to draw four ovals.

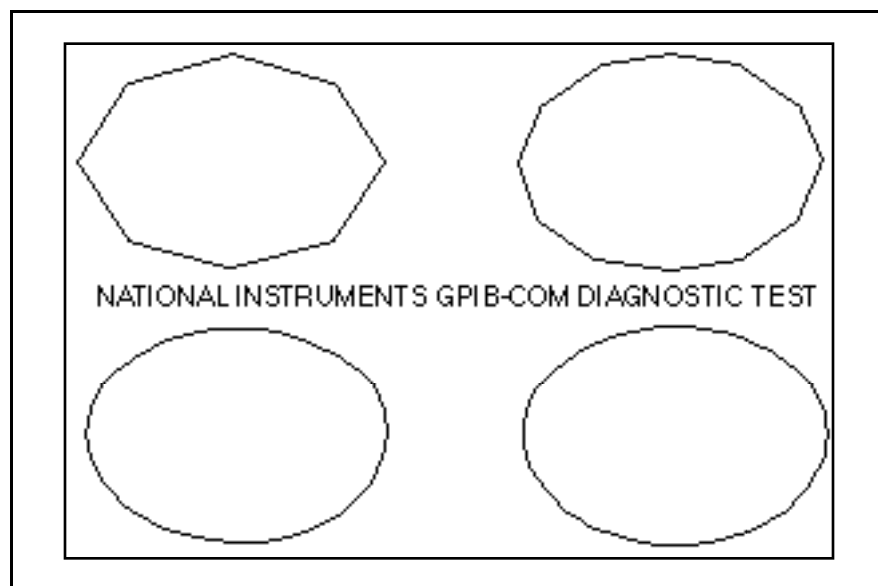


Figure 4-1. Plotter Output

When it is finished, the following message appears on the screen:

```
Plotter test finished.
```

```
Please check output to plotter with user manual instructions.
```

If the plotter does not respond or the output on the plotter does not match Figure 4-1, check again to be sure that all of the connections are tight and the jumpers are all set correctly. Try the test again. If it still does not work, write down any error messages that appear and call National Instruments.

-c change COM configuration

This command is used to change the base address of the GPIB-COM to match the actual board settings. If you have changed the jumper settings to something different than the default settings, you must run this command.

When this command is selected, the following menu appears:

```
This program assumes the GPIB-COM is configured at base address  
3F8 (COM1).
```

```
Enter the number of the correct address.
```

- 1) base address 3F8 (COM1)
- 2) base address 2F8 (COM2)

```
Enter 1, 2, or <return> for no change?
```

Type in the number of the address that you have configured the board to. The computer prints out your choice and returns to the main menu.

-q quit

This command ends the test program and returns to DOS.

Section Five

Programming the GPIB-COM

This section presents a description of the GPIB-COM Serial Port Emulator registers and information on programming the GPIB-COM. You need to use this section only if you are writing your own serial port device driver.

The GPIB-COM Registers

IBM's serial adapter is a plug-in card for the PC that handles RS-232 communication. The main component of the adapter is an INS8250 Asynchronous Communications chip or its equivalent, which is controlled by programming a set of registers on the I/O channel. The names of these registers and their I/O addresses are given in Table 5-1. Each register is located at a certain offset from the base address of the board. The addresses are given with an *X* for the first digit and a *Y* for the second digit, where *XY*=3F for COM1 (base address 3F8), *XY*=2F for COM2 (base address 2F8), *XY*=3E for COM3 (base address 3E8), and *XY*=2E for COM4 (base address 2E8). Notice that sometimes two registers share the same I/O address. The DLAB bit (bit 7 of the Line Control Register) determines which register will respond when these addresses are accessed.

Note: Throughout this section, the term *set* will be used to mean that a bit is a logical 1, and *clear* will mean that the bit is a logical 0.

Table 5-1. GPIB-COM Registers

Register	Type	I/O Address XY=3F for COM1 XY=2F for COM2 XY=3E for COM3 XY=2E for COM4	Offset from Base Address
Transmitter Holding Register	write	XY8 (DLAB=0)	0
Receive Buffer Register	read	XY8 (DLAB=0)	0
Divisor Latch LSB Register	read/write	XY8 (DLAB=1)	0
Divisor Latch MSB Register	read/write	XY9 (DLAB=1)	1
Interrupt Enable Register	read/write	XY9 (DLAB=0)	1
Interrupt Identification Register	read	XYA	2
Line Control Register	read/write	XYB	3
Modem Control Register	read/write	XYC	4
Line Status Register	read	XYD	5
Modem Status Register	read	XYE	6

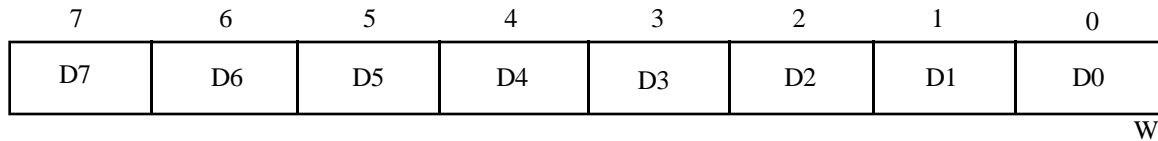
The following pages describe the functions of each register on the serial adapter and on the GPIB-COM. For a more complete description of the serial adapter, refer to the *IBM Options and Adapters Manual*.

Transmitter Holding Register

Offset from Base I/O Address = 0

Register Address = XF8

DLAB bit in Line Control Register = 0



The Transmitter Holding Register contains the character to be sent to the serial output, with bit 0 being the least significant and bit 7 the most significant. It functions identically on the GPIB-COM and the INS8250.

Bit	Mnemonic	Description
7-0w	D[7-0]	Data Bits 7 through 0

Receive Buffer Register

Offset from Base I/O Address = 0

Register Address = XF8

DLAB bit in Line Control Register = 0

7	6	5	4	3	2	1	0	R
D7	D6	D5	D4	D3	D2	D1	D0	

The Receive Buffer Register contains the character received from the serial input, with bit 0 being the least significant and bit 7 the most significant. It functions identically on the GPIB-COM and the INS8250.

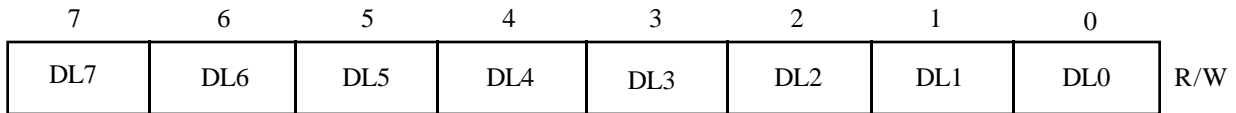
Bit	Mnemonic	Description
7-0r	D[7-0]	Data Bits 7 through 0

Divisor Latch Least Significant Byte (LSB) Register

Offset from Base I/O Address = 0

Register Address = XF8

DLAB bit in Line Control Register = 1



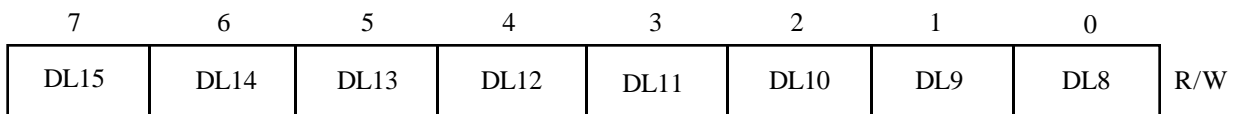
Bit	Mnemonic	Description
7-0r/w	DL[7-0]	Data Bits 7 through 0

Divisor Latch Most Significant Byte (MSB) Register

Offset from Base I/O Address = 1

Register Address = XF9

DLAB bit in Line Control Register = 1



The value stored in these two registers is used to determine the baud rate for serial communications. The 16-bit number formed by the Divisor Latch LSB and MSB is divided into a 1.8432 MHz clock to produce the baud rate.

The Divisor Latch Registers are ignored by the GPIB-COM circuitry; however, they are available on the GPIB-COM and can be written to and read by software.

Bit	Mnemonic	Description
7-0r/w	DL[15-8]	Data Bits 15 through 8

Interrupt Enable Register

Offset from Base I/O Address = 1

Register Address = XF9

DLAB bit in Line Control Register = 0

7	6	5	4	3	2	1	0	R/W
0	0	0	0	MS	RLS	THR	RDA	

The Interrupt Enable Register is a read/write register that allows the programmer to selectively enable or disable each of the four possible types of interrupts generated by the INS8250. The high four bits are not used and are permanently cleared. The lower four bits each enable one type of interrupt as listed below.

Bit	Mnemonic	Description
7-4r/w	0	Reserved Bits 7 through 4 These bits always read as 0.
3r/w	MS	Modem Status Interrupt Enable Bit This bit enables a modem status interrupt when set to logical 1. The modem status interrupt occurs when any of bits 0 through 3 of the Modem Status Register are set to logical 1. This bit is identical on the GPIB-COM and the INS8250, but bits 0 through 3 of the Modem Status Register are set for different conditions as noted under the Modem Status Register description.
2r/w	RLS	Receive Line Status Interrupt Enable Bit This bit enables a line status interrupt when set. The line status interrupt occurs when any of bits 1 through 4 of the Line Status Register become set. This bit is identical on the GPIB-COM and the INS8250, but bits 1 through 4 of the Line Status Register are set for different conditions as noted under the Line Status Register description.

Bit	Mnemonic	Description
1r/w	THR	<p>Transmitter Holding Register Interrupt Enable Bit</p> <p>This bit enables a transmitter holding register empty interrupt when set. The transmitter holding register empty interrupt occurs when the INS8250 becomes ready to send another character.</p> <p>This bit functions identically on the GPIB-COM and the INS8250.</p>
0r/w	RDA	<p>Received Data Available Interrupt Enable Bit</p> <p>This bit enables a received data available interrupt when set. The received data available interrupt occurs when a character is received from the serial input and stored in the Receive Buffer Register.</p> <p>This bit functions identically on the GPIB-COM and the INS8250.</p>

Interrupt Identification Register

Offset from Base I/O Address = 2

Register Address = XFA

7	6	5	4	3	2	1	0	R
0	0	0	0	0	ID1	ID0	INT	

The Interrupt Identification Register is a read-only register which tells you when an interrupt is pending and if so, what kind of interrupt it is. This register functions identically on the GPIB-COM and the INS8250.

Bit	Mnemonic	Description
7-3r	0	Reserved Bits 7 through 3 These bits always read as 0.
2-1r	ID[1-0]	Identify Interrupt Register Bits These two bits identify the interrupt that is pending. If more than one interrupt is pending, only the one with the highest priority is identified. The types and priorities are given in Table 5-2.

Table 5-2. Interrupt Types and Priorities

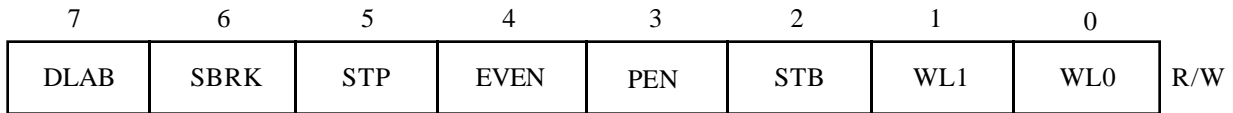
Bit 2	Bit 1	Type of Interrupt	Priority
0	0	Receiver Line Status	1st
0	1	Received Data Available	2nd
1	0	Transmitter Holding Register Empty	3rd
1	1	Modem Status	4th

0r	INT	Interrupt Pending Bit This bit is clear if an interrupt is pending. If set, no interrupt is pending.
----	-----	---

Line Control Register

Offset from Base I/O Address = 3

Register Address = XFB



The Line Control Register is a read/write register that allows the programmer to set the RS-232 parameters for the INS8250. The function of each bit in this register is explained below.

Bit	Mnemonic	Description
7r/w	DLAB	<p>Divisor Latch Access Bit</p> <p>This bit controls which registers will respond to I/O addresses XF8 and XF9. This bit is set to access the Divisor Latch LSB and MSB, and cleared to access the Transmitter Holding Register, the Receive Buffer Register, and the Interrupt Enable Register.</p> <p>This bit functions identically on the GPIB-COM and the INS8250.</p>
6r/w	SBRK	<p>Set Break Control Bit</p> <p>When set, this bit causes the SOUT line of the serial cable to be forced to a logical 0 state.</p> <p>This bit is ignored by the GPIB-COM.</p>
5r/w	STP	<p>Stick Parity Bit</p> <p>When this bit is set, the parity bit transmitted and detected will be the inverse of the EVEN bit (bit 4), regardless of the number of 1's in the data word.</p> <p>This bit is ignored by the GPIB-COM.</p>
4r/w	EVEN	<p>Even Parity Select Bit</p> <p>If this bit is set, even parity will be generated and checked. If this bit is clear, odd parity will be generated and checked.</p> <p>This bit is ignored by the GPIB-COM.</p>

Bit	Mnemonic	Description
3r/w	PEN	<p>Parity Enable Bit</p> <p>If this bit is set, the INS8250 will generate and check parity according to the values of the STP and EVEN bits (bits 4 and 5). If this bit is clear, the INS8250 will not generate or check parity bits.</p> <p>This bit is ignored by the GPIB-COM.</p>
2r/w	STB	<p>Stop Bit Control Bit</p> <p>This bit controls the number of stop bits sent and verified by the INS8250. If this bit is set, two stop bits will be used. If this bit is clear, one stop bit will be used.</p> <p>This bit is ignored by the GPIB-COM.</p>
1-0r/w	WL[1-0]	<p>Word Length Select Bits</p> <p>These two bits set the length of the words sent or received according to Table 5-3.</p>

Table 5-3. Word Length Select Bits

Bit 1	Bit 0	Word Length
0	0	5 bits
0	1	6 bits
1	0	7 bits
1	1	8 bits

These bits have no meaning on the GPIB and are ignored by the GPIB-COM circuitry.

Modem Control Register

Offset from Base I/O Address = 4

Register Address = XFC

7	6	5	4	3	2	1	0	R/W
0	0	0	LOOP	OUT2	OUT1	RTS	DTR	

The Modem Control Register is a read/write register that controls RS-232 output lines for communication with a modem or modem emulator. The function of each bit in this register is explained below.

Bit	Mnemonic	Description
7-5r/w	0	<p>Reserved Bits 7 through 5</p> <p>These bits always read as 0.</p>
4r/w	LOOP	<p>Loopback Diagnostic Test Bit</p> <p>When set, this bit internally connects the outputs of the INS8250 back to the inputs to allow the chip to be tested by writing data to itself and reading it back for verification.</p> <p>This bit is ignored by the GPIB-COM circuitry.</p>
3r/w	OUT2	<p>Auxiliary Output 2 Bit</p> <p>The OUT2 serial port output is the inverse of this bit. All interrupts from the serial adapter are disabled when this bit is cleared.</p> <p>When this bit is cleared, interrupts are disabled on the GPIB-COM.</p>
2r/w	OUT1	<p>Auxiliary Output 1 Bit</p> <p>The OUT1 serial port output is the inverse of this bit.</p> <p>This bit is ignored by the GPIB-COM circuitry.</p>
1r/w	RTS	<p>Request to Send Bit</p> <p>The RTS serial port output is the inverse of this bit. When this bit is set, it indicates that the Controller is ready to send data.</p> <p>On the GPIB-COM, this bit is used along with the DTR bit to control the CTS bit of the Modem Status Register.</p>

Bit	Mnemonic	Description
Or/w	DTR	Data Terminal Ready Bit The DTR serial port output is the inverse of this bit. This bit is set when the Controller is ready to communicate. On the GPIB-COM, this bit is used along with the RTS bit to control the CTS bit of the Modem Status Register.

Line Status Register

Offset from Base I/O Address = 5

Register Address = XFD

7	6	5	4	3	2	1	0	R
0	TEMT	THRE	BI	FE	PE	OE	DR	

The Line Status Register provides information about the status of the data transfer. On the GPIB-COM this register is implemented as a read-only register. Writing to the line status register will not change its contents. The function of each bit in this register is explained below.

Bit	Mnemonic	Description
7r	0	Reserved Bit This bit always reads as 0.
6r	TEMT	Transmitter Shift Register Empty Bit This bit is cleared when a character is transferred from the Transmitter Holding Register to the Transmitter Shift Register and set when the character has been shifted out of the Shift Register onto the serial output line. On the GPIB-COM, there is no shift register so this bit behaves exactly the same as the THRE bit.
5r	THRE	Transmitter Holding Register Empty Bit This bit is cleared when the processor writes a character into the Transmitter Holding Register and set when the character has been transmitted and the INS8250 is ready to send another character. This bit functions identically on the GPIB-COM and the INS8250.
4r	BI	Break Interrupt Bit This bit is set to logical 1 when the serial data input remains in the logical 0 state for longer than one full word transmission time. On the GPIB-COM, this bit is always clear.

Bit	Mnemonic	Description
3r	FE	<p>Framing Error Bit</p> <p>This bit is set when the received character does not have a valid stop bit.</p> <p>On the GPIB-COM, this bit is always clear.</p>
2r	PE	<p>Parity Error Bit</p> <p>This bit is set when the received character does not have the correct parity. It is cleared when the processor reads the Line Status Register.</p> <p>On the GPIB-COM, this bit is set when the SRQ* line of the GPIB is asserted. When the special function selection DIP switch has been set to disable the SRQ feature, this bit is always clear.</p>
1r	OE	<p>Overrun Error Bit</p> <p>This bit is set when a new character is received and stored in the Receive Buffer Register before the processor reads the previous character, thus overwriting and destroying the previous character. It is cleared when the processor reads the Line Status Register.</p> <p>On the GPIB-COM, this bit is always clear.</p>
0r	DR	<p>Data Ready Bit</p> <p>This bit is set when a character has been received and stored in the Receive Buffer Register. It is cleared when the processor reads the Receive Buffer Register.</p> <p>This bit functions identically on the GPIB-COM and the INS8250.</p>

Modem Status Register

Offset from Base I/O Address = 6

Register Address = XFE

7	6	5	4	3	2	1	0 R
DCD	RI	DSR	CTS	DDCD	TERI	DDSR	DCTS

The Modem Status Register gives the state of the modem control lines and tells whether any of these lines have changed state since the register was last read. This register is read only on the GPIB-COM. Writing to this register will not change its contents. The function of each bit in this register is explained below.

Bit	Mnemonic	Description
7r	DCD	<p>Data Carrier Detect Bit</p> <p>This bit reflects the inverse of the serial port DCD input signal.</p> <p>On the GPIB-COM, this bit is always clear.</p>
6r	RI	<p>Ring Indicator Bit</p> <p>This bit reflects the inverse of the serial port RI input signal.</p> <p>On the GPIB-COM, this bit is always clear.</p>
5r	DSR	<p>Data Set Ready Bit</p> <p>This bit reflects the inverse of the serial port DSR input signal.</p> <p>On the GPIB-COM, this bit is always set to indicate that the interface is ready to transfer data.</p>
4r	CTS	<p>Clear to Send Bit</p> <p>This bit reflects the inverse of the serial port CTS input signal.</p> <p>On the GPIB-COM, this bit is the logical AND of the DTR and RTS bits of the Modem Control Register.</p>
3r	DDCD	<p>Delta Data Carrier Detect Bit</p> <p>This bit is set when the serial port DCD input signal changes state and cleared when the processor reads the Modem Status Register.</p> <p>On the GPIB-COM, this bit is always clear.</p>

Bit	Mnemonic	Description
2r	TERI	<p>Trailing Edge Ring Indicator Bit</p> <p>This bit is set when the serial port RI input signal changes from a logical 1 to a logical 0 and cleared when the processor reads the Modem Status Register.</p> <p>On the GPIB-COM, this bit is always clear.</p>
1r	DDSR	<p>Delta Set Ready Bit</p> <p>This bit is set when the serial port DSR input signal changes state and cleared when the processor reads the Modem Status Register.</p> <p>On the GPIB-COM, this bit is always clear.</p>
0r	DCTS	<p>Delta Clear to Send Bit</p> <p>This bit is set when the CTS input changes state and cleared when the processor reads the Modem Status Register.</p> <p>On the GPIB-COM, this bit is the logical AND of the DTR and RTS bits of the Modem Control Register.</p>

Programming the Serial Adapter

The operation of the serial adapter is controlled by software, either IBM BIOS or an application. To transfer data to and from the serial port, the communications parameters must first be set up in the following manner:

1. Load the baud rate divisor into the divisor latch.
2. Store the RS-232 parameters in the Line Control Register.
3. Send the modem control signals by writing to the Modem Control Register.
4. Enable interrupts, if used, by writing to the appropriate bits in the Interrupt Enable Register.

Once the control registers have been programmed correctly, the software can transmit and receive serial data by polling, interrupts, or both.

Polling Method

In the polled method of operation, the Line Status Register is continuously read to check if the Data Ready Bit is set. When this bit becomes set, the Receive Buffer Register is read to get the character that just came from the serial port, and the process continues. To transmit data, the Line Status Register is polled until the Transmitter Holding Register Empty Bit is set. A byte can then be written to the Transmitter Holding Register, and polling continues.

Interrupt-Driven Method

In the interrupt-driven mode of operation, the desired interrupts are enabled through the OUT2 bit and the Interrupt Enable Register. An interrupt handler is installed to respond when an interrupt occurs. Software processes can perform other tasks until an interrupt is received. When an interrupt occurs, the handler reads the Interrupt Identification Register to determine the type of interrupt and takes appropriate action, such as reading the Receive Buffer Register in the case of a received data available interrupt, writing to the Transmitter Holding Register if it was a THRE interrupt, or printing an error message in the case of a line status interrupt.

The GPIB-COM Controller Function

Because most serial port applications involve communication with only one serial line, the GPIB-COM imposes some restrictions on the GPIB in order to be compatible with existing serial port software. The GPIB-COM must be System Controller of the GPIB and will not work with other Controllers. The behavior of the GPIB-COM depends on the setting of the talk-only jumper.

If the jumper is set to talk-only, the GPIB-COM assumes that there is a listen-only device connected to the GPIB. When a byte is written into the Transmitter Holding Register, the GPIB-COM sets the THRE bit of the Line Status Register to 0, puts the contents of that register on the GPIB data lines, and begins the source handshake sequence. When the Listener releases NDAC*, the THRE bit is set back to 1 and the GPIB-COM waits for another byte to be written into the Transmitter Holding Register.

If the jumper is set to talk/listen, the GPIB-COM assumes that the device connected to the GPIB can be addressed to listen or talk. When the computer is powered on, the GPIB-COM sends the talk address that is set on the DIP switches, addresses itself as a Listener, and unasserts NRFD*. If the GPIB device sends a byte, the GPIB-COM accepts it, stores it in the Receive Buffer Register, and sets the DR bit of the Line Status Register. At the end of the GPIB handshake, it keeps NRFD* asserted until the computer reads the byte from the Receive Buffer Register.

If the computer writes a byte to the Transmitter Holding Register, the GPIB-COM sends the GPIB device its listen address from the DIP switches and addresses itself to talk. Then it sends the byte to the GPIB device, which is now addressed as a Listener. When the GPIB-COM begins a source handshake, it starts a 200-msec timer. If the source handshake is completed before the 200 msec is expired, the GPIB-COM remains addressed to talk until the timer runs out. If the computer writes another byte before the timer runs out, the GPIB-COM restarts the timer and sends the byte. When 200 msec has passed since the last byte was written, the GPIB-COM sends the talk address and addresses itself to listen again. If a byte was waiting in the Receive Buffer Register when the computer wrote to the Transmitter Holding Register, the GPIB-COM remembers this and when it becomes a Listener again, it asserts NRFD* until the computer reads the byte from the Receive Buffer Register.

Appendix A

Specifications

This appendix lists the specifications of the GPIB-COM board.

Power Requirement

+5 VDC ($\pm 5\%$) 0.75 A typical

Physical

Dimensions 4.2 in. by 8.75 in.

I/O Connector IEEE-488 Standard 24-pin

Operating Environment

Component Temperature 0° to 70° C

Relative Humidity 5% to 90%, noncondensing

Emissions FCC Class B

Storage Environment

Temperature -55° to 125° C

Relative Humidity 5% to 90%, noncondensing

Appendix B

Multiline Interface Command Messages

The following tables are multiline interface messages (sent and received with ATN TRUE).

Multiline Interface Messages

Hex	Oct	Dec	ASCII	Msg	Hex	Oct	Dec	ASCII	Msg
00	000	0	NUL		20	040	32	SP	MLA0
01	001	1	SOH	GTL	21	041	33	!	MLA1
02	002	2	STX		22	042	34	"	MLA2
03	003	3	ETX		23	043	35	#	MLA3
04	004	4	EOT	SDC	24	044	36	\$	MLA4
05	005	5	ENQ	PPC	25	045	37	%	MLA5
06	006	6	ACK		26	046	38	&	MLA6
07	007	7	BEL		27	047	39	'	MLA7
08	010	8	BS	GET	28	050	40	(MLA8
09	011	9	HT	TCT	29	051	41)	MLA9
0A	012	10	LF		2A	052	42	*	MLA10
0B	013	11	VT		2B	053	43	+	MLA11
0C	014	12	FF		2C	054	44	,	MLA12
0D	015	13	CR		2D	055	45	-	MLA13
0E	016	14	SO		2E	056	46	.	MLA14
0F	017	15	SI		2F	057	47	/	MLA15
10	020	16	DLE		30	060	48	0	MLA16
11	021	17	DC1	LLO	31	061	49	1	MLA17
12	022	18	DC2		32	062	50	2	MLA18
13	023	19	DC3		33	063	51	3	MLA19
14	024	20	DC4	DCL	34	064	52	4	MLA20
15	025	21	NAK	PPU	35	065	53	5	MLA21
16	026	22	SYN		36	066	54	6	MLA22
17	027	23	ETB		37	067	55	7	MLA23
18	030	24	CAN	SPE	38	070	56	8	MLA24
19	031	25	EM	SPD	39	071	57	9	MLA25
1A	032	26	SUB		3A	072	58	:	MLA26
1B	033	27	ESC		3B	073	59	;	MLA27
1C	034	28	FS		3C	074	60	<	MLA28
1D	035	29	GS		3D	075	61	=	MLA29
1E	036	30	RS		3E	076	62	>	MLA30
1F	037	31	US		3F	077	63	?	UNL

Message Definitions

DCL	Device Clear	MSA	My Secondary Address
GET	Group Execute Trigger	MTA	My Talk Address
GTL	Go To Local	PPC	Parallel Poll Configure
LLO	Local Lockout	PPD	Parallel Poll Disable
MLA	My Listen Address		

Multiline Interface Messages

Hex	Oct	Dec	ASCII	Msg	Hex	Oct	Dec	ASCII	Msg
40	100	64	@	MTA0	60	140	96	`	MSA0,PPE
41	101	65	A	MTA1	61	141	97	a	MSA1,PPE
42	102	66	B	MTA2	62	142	98	b	MSA2,PPE
43	103	67	C	MTA3	63	143	99	c	MSA3,PPE
44	104	68	D	MTA4	64	144	100	d	MSA4,PPE
45	105	69	E	MTA5	65	145	101	e	MSA5,PPE
46	106	70	F	MTA6	66	146	102	f	MSA6,PPE
47	107	71	G	MTA7	67	147	103	g	MSA7,PPE
48	110	72	H	MTA8	68	150	104	h	MSA8,PPE
49	111	73	I	MTA9	69	151	105	i	MSA9,PPE
4A	112	74	J	MTA10	6A	152	106	j	MSA10,PPE
4B	113	75	K	MTA11	6B	153	107	k	MSA11,PPE
4C	114	76	L	MTA12	6C	154	108	l	MSA12,PPE
4D	115	77	M	MTA13	6D	155	109	m	MSA13,PPE
4E	116	78	N	MTA14	6E	156	110	n	MSA14,PPE
4F	117	79	O	MTA15	6F	157	111	o	MSA15,PPE
50	120	80	P	MTA16	70	160	112	p	MSA16,PPD
51	121	81	Q	MTA17	71	161	113	q	MSA17,PPD
52	122	82	R	MTA18	72	162	114	r	MSA18,PPD
53	123	83	S	MTA19	73	163	115	s	MSA19,PPD
54	124	84	T	MTA20	74	164	116	t	MSA20,PPD
55	125	85	U	MTA21	75	165	117	u	MSA21,PPD
56	126	86	V	MTA22	76	166	118	v	MSA22,PPD
57	127	87	W	MTA23	77	167	119	w	MSA23,PPD
58	130	88	X	MTA24	78	170	120	x	MSA24,PPD
59	131	89	Y	MTA25	79	171	121	y	MSA25,PPD
5A	132	90	Z	MTA26	7A	172	122	z	MSA26,PPD
5B	133	91	[MTA27	7B	173	123	{	MSA27,PPD
5C	134	92	\	MTA28	7C	174	124		MSA28,PPD
5D	135	93]	MTA29	7D	175	125	}	MSA29,PPD
5E	136	94	^	MTA30	7E	176	126	~	MSA30,PPD
5F	137	95	_	UNT	7F	177	127	DEL	

PPE Parallel Poll Enable
 PPU Parallel Poll Unconfigure
 SDC Selected Device Clear
 SPD Serial Poll Disable

SPE Serial Poll Enable
 TCT Take Control
 UNL Unlisten
 UNT Untalk

Appendix C

Operation of the GPIB

History of the GPIB

The GPIB is a link, bus, or interface system through which interconnected electronic devices communicate. Hewlett-Packard invented the GPIB, which they call the HP-IB, to connect and control programmable instruments manufactured by them. Because of its high system data rate ceilings of from 250 kbytes/sec to 1 Mbyte/sec, the GPIB quickly became popular in other applications such as intercomputer communication and peripheral control. It was later accepted as the industry standard IEEE-488. The versatility of the system prompted the name General Purpose Interface Bus.

Types of Messages

Devices on the GPIB communicate by passing messages through the interface system. There are two types of messages:

- Device-dependent messages, often called data or data messages, contain device-specific information such as programming instructions, measurement results, machine status, and data files.
- Interface messages manage the bus itself. They are usually called commands or command messages. Interface messages perform such functions as initializing the bus, addressing and unaddressing devices, and setting devices for remote or local programming.

Note: The term *command* as used here should not be confused with some device instructions which are also called commands. Such device-specific instructions are actually data messages.

Talkers, Listeners, and Controllers

There are three types of GPIB communicators. A Talker sends data messages to one or more Listeners. The Controller manages the flow of information on the GPIB by sending commands to all devices.

Devices can be Talkers, Listeners, and/or Controllers. A digital multimeter, for example, is a Talker and may also be a Listener. A printer or plotter is usually only a Listener. A computer on the GPIB often combines all three roles to manage the bus and communicate with other devices. The GPIB is a bus like a typical computer bus except that the computer has its circuit cards interconnected via a backplane bus whereas the GPIB has standalone devices interconnected via a cable bus.

The role of the GPIB Controller can also be compared to the role of the computer's CPU, but a better analogy is to the switching center of a city telephone system.

The switching center (Controller) monitors the communications network (GPIB). When the center (Controller) notices that a party (device) wants to make a call (send a data message), it connects the caller (Talker) to the receiver (Listener).

The Controller usually addresses a Talker and a Listener before the Talker can send its message to the Listener. After the message is transmitted, the Controller usually unaddresses both devices.

Some bus configurations do not require a Controller. For example, one device may only be a Talker (called a talk-only device) and there may be one or more listen-only devices.

A Controller is necessary when the active or addressed Talker or Listener must be changed. The Controller function is usually handled by a computer.

System Controller and Active Controller

Although there can be multiple Controllers on the GPIB, only one Controller at a time is Active Controller or Controller-in-Charge. Active control can be passed from the current Active Controller to an idle Controller. Only one device on the bus, the System Controller, can make itself the Active Controller.

GPIB Signals

The interface bus consists of 16 signal lines and 8 ground return or shield drain lines. The 16 signal lines are divided into three groups:

- eight data lines
- three handshake lines
- five interface management lines

Figure C-1 shows the arrangement of these signals on the GPIB cable connector.

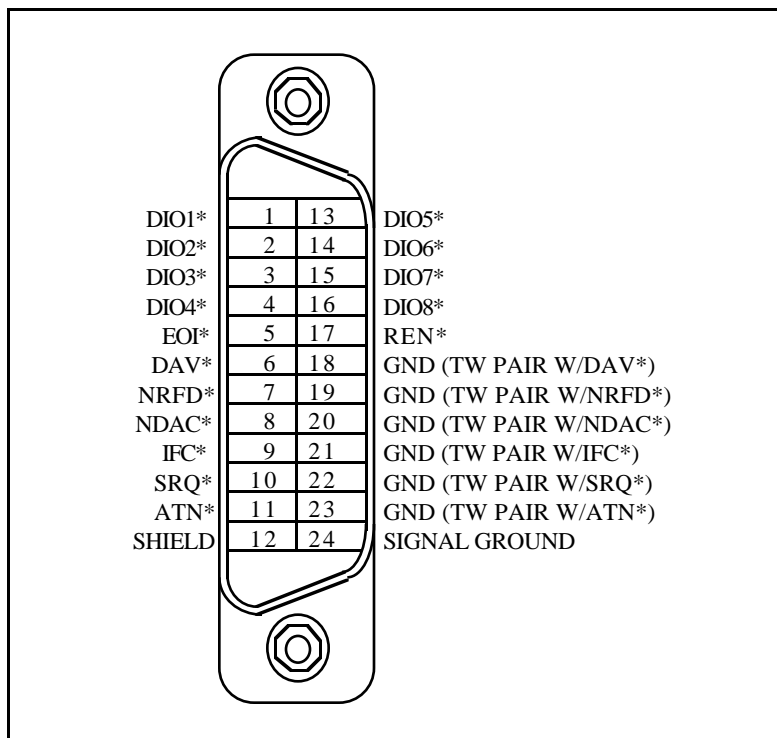


Figure C-1. GPIB Cable Connector

Data Lines

The eight data lines, DIO1 through DIO8, carry both data and command messages. All commands and most data use the 7-bit ASCII or ISO code set, in which case the eighth bit, DIO8, is unused or used for parity.

Handshake Lines

Three lines asynchronously control the transfer of message bytes among devices. The process is called a three-wire interlocked handshake and it guarantees that message bytes on the data lines are sent and received without transmission error.

NRFD (not ready for data)

NRFD indicates when a device is ready or not ready to receive a message byte. The line is driven by all devices when receiving commands and by Listeners when receiving data messages.

NDAC (not data accepted)

NDAC indicates when a device has or has not accepted a message byte. The line is driven by all devices when receiving commands and by Listeners when receiving data messages.

DAV (data valid)

DAV tells when the signals on the data lines are stable (valid) and can be accepted safely by devices. The Controller drives DAV when sending commands, and the Talker drives it when sending data messages.

The way in which NRFD and NDAC are used by the receiving device is called the Acceptor Handshake. Likewise, the sending device uses DAV in the Source Handshake.

Interface Management Lines

Five lines are used to manage the flow of information across the interface.

ATN (attention)

The Controller drives ATN true when it uses the data lines to send commands and false when it allows a Talker to send data messages.

IFC (interface clear)

The System Controller drives the IFC line to initialize the bus to become Controller-In-Charge.

REN (remote enable)

The System Controller drives the REN line, which is used to place devices in remote or local program mode.

SRQ (service request)

Any device can drive the SRQ line to asynchronously request service from the Active Controller.

EOI (end or identify)

The EOI line has two purposes. The Talker uses the EOI line to mark the end of a message string. The Active Controller uses the EOI line to tell devices to identify their responses in a parallel poll.

Physical and Electrical Characteristics

Devices are usually connected with a cable assembly consisting of a shielded 24-conductor cable with both a plug and receptacle at each end. This design enables devices to be connected in either a linear or a star configuration, or a combination of the two. See Figures C-2 and C-3.

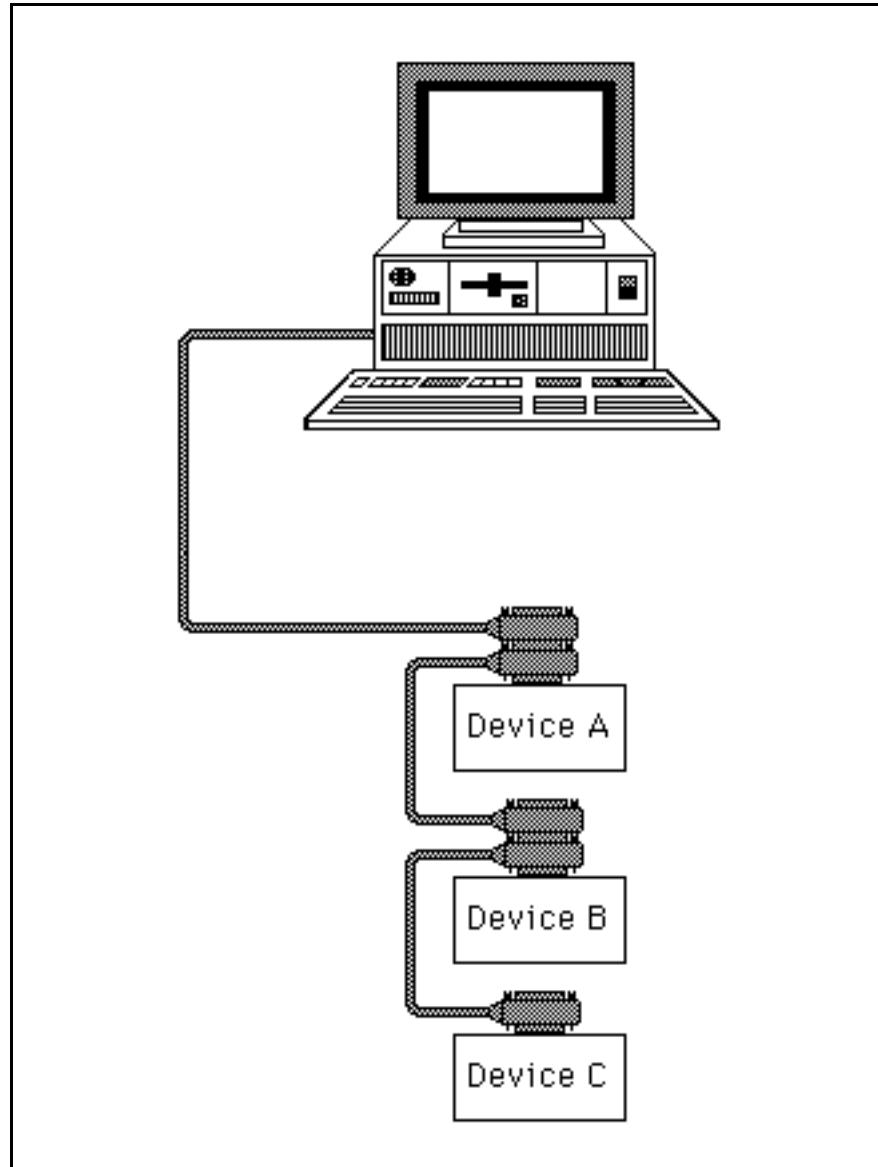


Figure C-2. Linear Configuration of the GPIB Devices

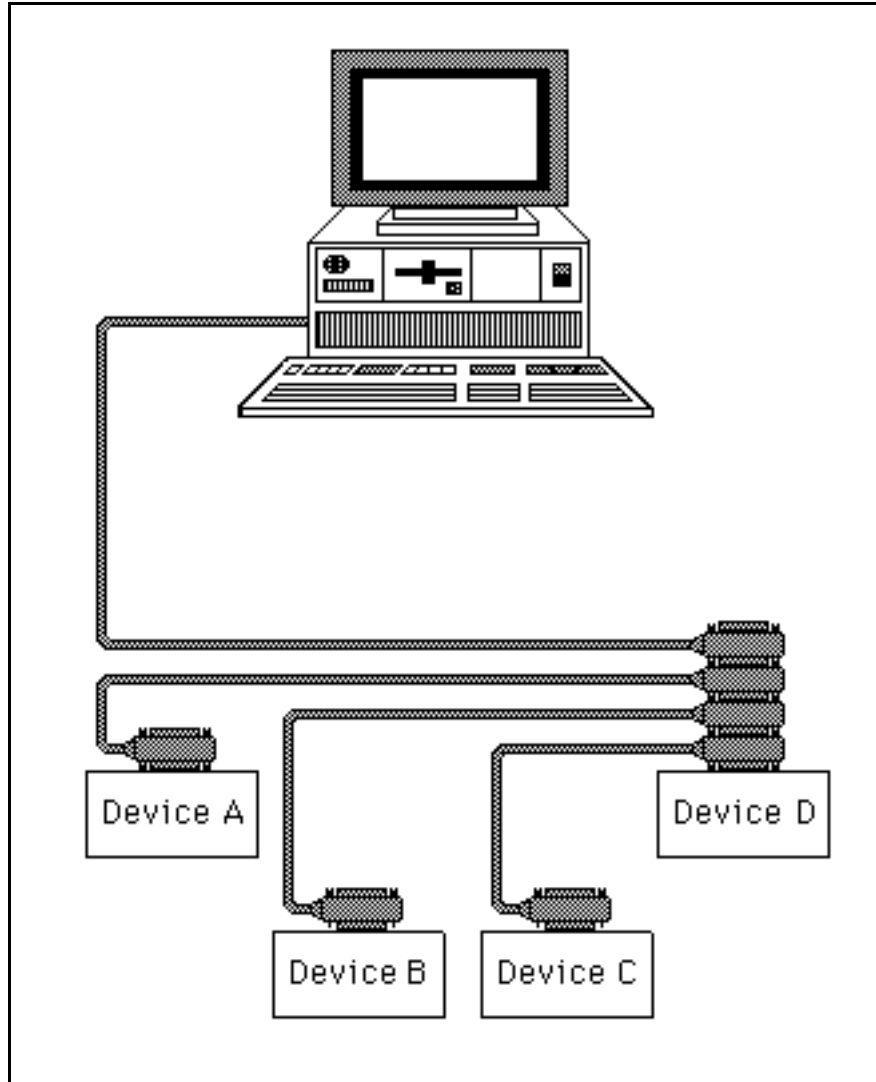


Figure C-3. Star Configuration of GPIB Devices

The standard connector is the Amphenol or Cinch Series 57 MICRORIBBON or AMP CHAMP type. An adapter cable using non-standard cable and/or connector is used for special interconnect applications.

The GPIB uses negative logic with standard TTL logic levels. When DAV is true, for example, it is a TTL low level (≤ 0.8 V), and when DAV is false, it is a TTL high level (≥ 2.0 V).

Configuration Restrictions

To achieve the high data transfer rate that the GPIB is designed for, the physical distance between devices and the number of devices on the bus is limited.

The following restrictions are typical:

- A maximum separation of 4 m between any two devices and an average separation of 2 m over the entire bus.
- A maximum total cable length of 20 m.
- No more than 15 devices connected to each bus, with at least two-thirds powered-on.

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